

# Interpretation of point forecasts with unknown directive

Patrick Schmidt  
(joint with Tilmann Gneiting and Matthias Katzfuss)

Heidelberg Institute for Theoretical Studies and Goethe University Frankfurt

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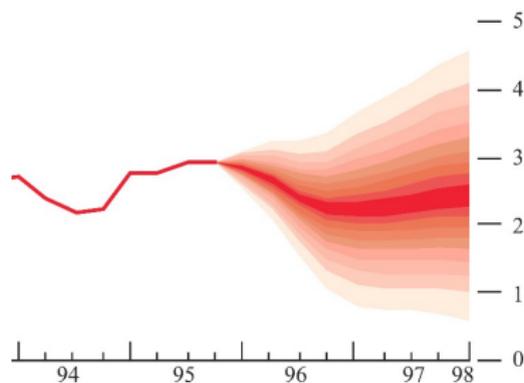


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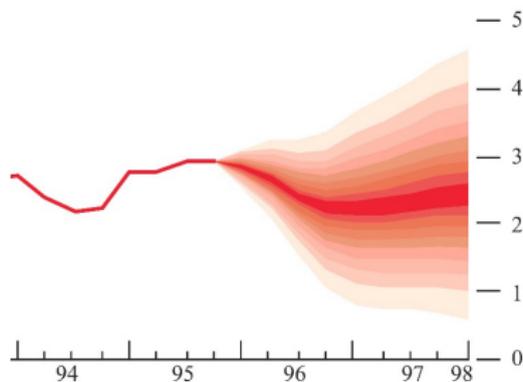


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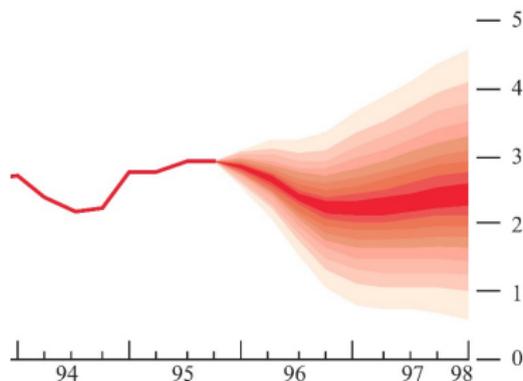


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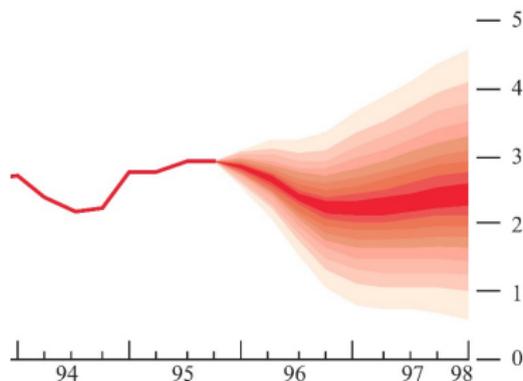


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(Manski, 2016; Elliott and Timmermann, 2008; Engelberg et al., 2009; Gneiting, 2011)
  
- ▶ How can we conceptualize and estimate the directive?
  - ▶ Elliott et al. (2005) and Patton and Timmermann (2007) propose to estimate the underlying loss function

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- ▶ We show how to identify the functional based on forecast and realization alone
- ▶ We propose a GMM-estimator for state-dependent quantile (expectile) forecasts
- ▶ We find that the Federal Reserves' GDP forecasts are quantiles that depend on the current growth level

# Outline

Setting

Identification

Parametric estimation

Application

MCS

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- ▶ The functional  $\alpha$  and the conditional distributions  $\mathcal{L}(Y_t | \mathcal{F}_t)$  are unobservable
  
- ▶ We want to do inference on  $\alpha$

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# Identification

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- ▶ We show that, for well-behaved  $\alpha$ , there exists an *identification function*  $V_\alpha$ , such that

$$X = \alpha(Y|\mathcal{F}) \iff \mathbb{E}[V_\alpha(X, Y) \cdot W] = 0 \text{ for all } W \in \mathcal{F}.$$

(Proof: Steinwart et al. (2014) + Gneiting et al. (2007))

# Loss functions

- ▶ Previous work (Elliott et al., 2005; Patton and Timmermann, 2007) defined optimal point forecasts with loss functions  $L(x, y)$  by

$$X = \arg \min_{x \in \mathbb{R}} \mathbb{E}[L(x, Y) | \mathcal{F}]. \quad (1)$$

- ▶ Defines a functional
- ▶ There exist many loss functions (Gneiting, 2011; Ehm et al., 2016) for one functional  
⇒ It is impossible to identify the loss function.

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specification name	model	$\Theta$
constant	$m(z, \theta) = \theta$	$(0, 1)$
break	$m(z, \theta) = \mathbb{1}(z > t_b)\theta_1 + \mathbb{1}(z \leq t_b)\theta_2$	$(0, 1)^2$
linear	$m(z, \theta) = \Psi(\theta_1 + z \cdot \theta_2)$	$[a, b]^2$
periodic	$m(z, \theta) = \Psi(\theta_1 + \theta_2 \sin(2\pi z/\theta_3))$	$[a, b]^3$

# GMM-Estimation

- ▶  $X = q_{m(Z, \theta_0)}(Y | \mathcal{F})$  implies

$$\mathbb{E}[(\mathbb{1}(Y \leq X) - m(Z, \theta_0)) \cdot W] = 0.$$

- ▶ Empirical mean is

$$g_T(\theta) := \frac{1}{T} \sum_{t=1}^T (\mathbb{1}(y_t \leq x_t) - m(z_t, \theta)) \cdot w_t.$$

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If  $m$  is continuous, there exists an  $\mathcal{F}_t$ -measurable instrumental variable  $W_t$  such that

$$\hat{\theta}_T \xrightarrow{P} \theta_0.$$

## Testing optimality

- ▶ Test of overidentifying restrictions (Hansen, 1982): If the forecast is optimal, it holds that

$$J_T(\hat{\theta}_T) \xrightarrow{D} \chi_{q-p}^2, \text{ as } T \rightarrow \infty,$$

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- ▶ If  $X$  is optimal with respect to  $\mathcal{F}$ , then it is also optimal with respect to any smaller information set.
- ▶ We can test hypothesis  $H_0$ :

There exists a  $\theta \in \Theta$  such that  $X = q_{m(z,\theta)}(Y|\mathcal{F})$  with  $\sigma(w) \subset \mathcal{F}$ .

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# Application: GDP forecast

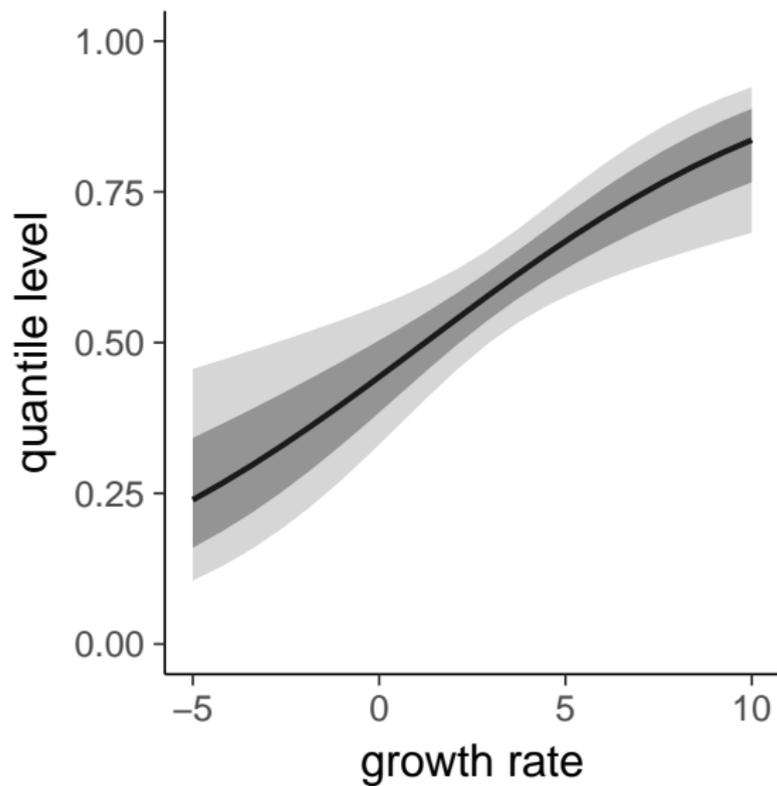
- ▶ Consider the Greenbook GDP growth forecasts of the Federal Reserve
  - ▶ quarterly real GDP growth rate forecasts over the period 1968 to 2011 ( $T = 172$  observations)
  - ▶ standard tests of optimality based on the mean functional reject the optimality of the forecast (Patton and Timmermann, 2007)

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- ▶ We interpret the forecasts as a state-dependent quantile

$$m(z_t, \theta) = m(x_t, \theta) = \Psi(\theta_1 + x_t \cdot \theta_2).$$

# Results



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- ▶ Data-generating process:

$$Y_t = \frac{1}{2}Y_{t-1} + \sigma_t\epsilon_t \quad \text{for } t = 1, 2, \dots, T,$$
$$\sigma_t^2 = .1 + .8\sigma_{t-1}^2 + .1\sigma_{t-1}^2\epsilon_{t-1}^2,$$
$$\epsilon_t \stackrel{iid}{\sim} \mathcal{N}(0, 1).$$

- ▶ Generate on each data set optimal forecasts and different optimality tests

# Constant quantile forecast

- ▶ A fully informed 1-step ahead forecast

$$x_t = \frac{1}{2} Y_{t-1} - \frac{1}{4} \sigma_t.$$

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$$x_t = \frac{1}{4} Y_{t-2} + 1.15 \sigma_{t-1}^2 + .1$$

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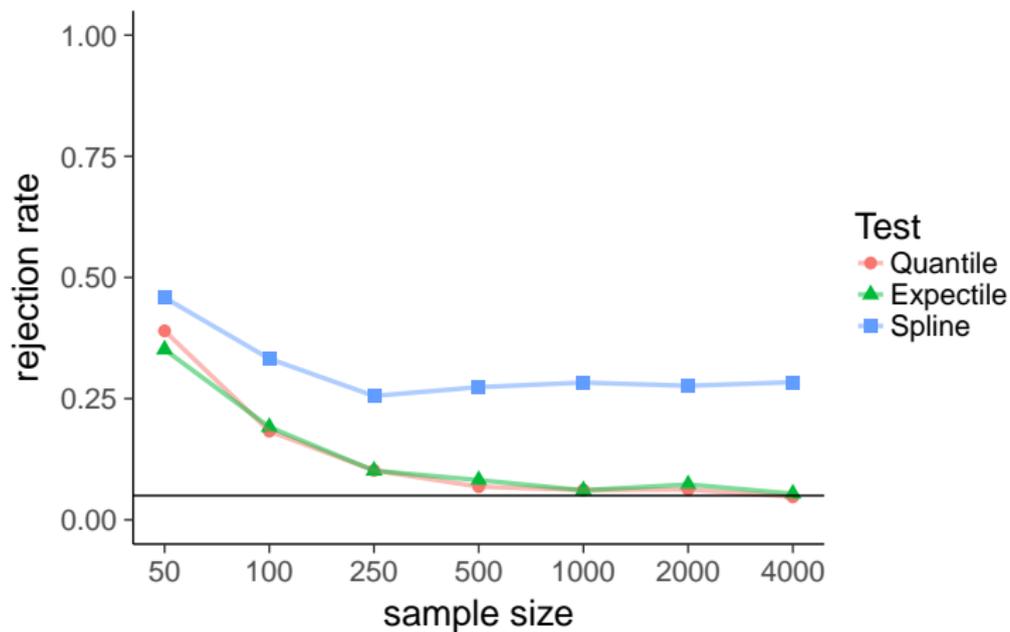
$$x_t = \frac{1}{2} Y_{t-1} - \frac{1}{4} \sigma_t.$$

- ▶ A 2-step ahead forecast

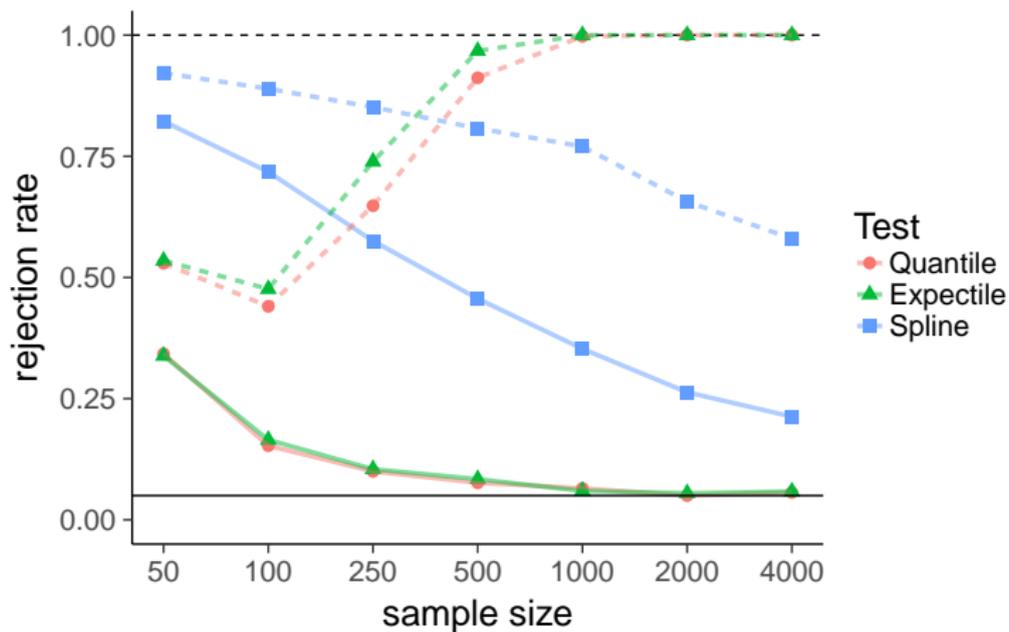
$$x_t = \frac{1}{4} Y_{t-2} + 1.15 \sigma_{t-1}^2 + .1$$

- ▶ We apply optimality tests of linear specification models for
  - ▶ quantiles,
  - ▶ expectiles,
  - ▶ and the spline test of Patton and Timmermann (2007)with normal and with lagged instruments.

## Results for 1-step ahead forecast



## Results for 2-step ahead forecast



# Different state-dependent forecasts

- ▶ We generated three optimal state-dependent forecasts
  - ▶ a quantile forecast that depends linearly on the current time series value (*linear*)
  - ▶ one that is subject to periodic deviations (*periodic*)
  - ▶ one that is exposed to a break at half the sample size (*break*)

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- ▶ To each forecast we apply a test of optimality based on the linear, periodic and break specification model.

## Results: rejection rates

$T = 1000$

	forecast model	test model		
		linear	periodic	break
linear		0.059	1.000	1.000
periodic		1.000	0.057	1.000
break		1.000	1.000	0.059

## Results: rejection rates

$T = 1000$	forecast model		test model		
		linear	periodic	break	
	linear	0.059	1.000	1.000	
	periodic	1.000	0.057	1.000	
break	1.000	1.000	0.059		

$T = 100$	forecast model		test model		
		linear	periodic	break	
	linear	0.092	0.643	0.784	
	periodic	0.844	0.076	0.619	
break	0.673	0.373	0.087		

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- ▶ State-dependent quantiles/expectiles can be used to interpret point forecasts coherently
- ▶ Applications possible in
  - ▶ comparison of point and probability forecasts
  - ▶ backtesting of risk measures
  - ▶ creating density forecasts from multiple point forecasts

# References I

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# Connection to Mincer-Zarnowitz test

- ▶ Procedure of Mincer-Zarnowitz optimality test

1. OLS regression  $Y = \beta_0 + \beta_1 X + u$
2. Test  $H_0: \beta_0 = 0 \wedge \beta_1 = 1$

- ▶ Mincer-Zarnowitz test is equivalent to

1. Assume optimal forecast

$$X = \beta_0 + \beta_1 \mathbb{E}[Y|X]$$

2. Derive identification function

$$\mathbb{E}[(\beta_0 + \beta_1 X - Y)|\mathcal{F}] = 0$$

3. Apply GMM-estimator with instruments  $W = (1, X)$
4. Test  $H_0: \beta_0 = 0 \wedge \beta_1 = 1$