

## Online Appendix

### Term Limits and Bargaining Power in Electoral Competition

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*Proof of Lemma 1.* Consider a challenger  $i$  who first runs in period  $t$  against an incumbent of type  $(\theta, k)$ . Let  $R(\theta')$  be  $i$ 's expected lifetime rents from office, conditional on winning in period  $t$  and on her ability being  $\theta'$ . Let  $\gamma Q(\theta')$  be  $i$ 's expected lifetime policy payoffs **excluding period  $t$** , again conditional on winning in period  $t$  and her ability being  $\theta'$ . Let  $\gamma S_k(\theta, \theta')$  be  $i$ 's policy payoff in period  $t$ , conditional on her ability being  $\theta'$  and the incumbent being type  $(\theta, k)$ . (Note that  $R(\theta')$ ,  $Q(\theta')$  are independent of  $\theta$  and  $k$ , and  $R$ ,  $Q$  and  $S$  are *not* functions of  $\gamma$ .) Then

$$T_k(\theta) = \int_0^1 [R(\theta') + \gamma Q(\theta') + \gamma S_k(\theta, \theta')] r_k(\theta, \theta') f(\theta') d\theta'.$$

By Proposition 1, if the challenger wins and her ability is  $\theta'$ , then with probability  $1-\mu$  she is unbiased, her policy is 0, and her policy payoff is 0; with probability  $\mu$  she is biased, her policy is  $\pm \sqrt{\frac{U_0(\theta') - U_k(\theta)}{\lambda}}$ , and her policy payoff is  $-\left(I - \sqrt{\frac{U_0(\theta') - U_k(\theta)}{\lambda}}\right)^2$ .

In other words,  $S_k(\theta, \theta') = -\mu \left(I - \sqrt{\frac{U_0(\theta') - U_k(\theta)}{\lambda}}\right)^2$ , which is a strictly decreasing function of  $U_k(\theta)$ . Furthermore,  $r_k(\theta, \theta')$  is weakly decreasing as a function of  $U_k(\theta)$  for each  $\theta'$ : if  $U_k(\theta) < U_{\tilde{k}}(\tilde{\theta})$ , then either  $U_k(\theta) < U_0(\theta')$ , implying  $r_k(\theta, \theta') = 1 \geq r_{\tilde{k}}(\tilde{\theta}, \theta')$ , or  $U_0(\theta') < U_{\tilde{k}}(\tilde{\theta})$ , implying  $r_k(\theta, \theta') \geq r_{\tilde{k}}(\tilde{\theta}, \theta') = 0$ . The result follows.  $\square$

*Proof of Proposition 5–Pinning down  $\theta_0$ .* Under stationary limits, the expressions for

$R$  and  $Q$  simplify to

$$R(\theta) = \frac{b}{1 - \delta p(1 - q(\theta)\kappa(\theta))} = \frac{b}{1 - \delta p + \delta p q(\theta)\kappa(\theta)}$$

$$Q(\theta) = [q(\theta)y_1 + (1 - q(\theta))y_0] \frac{\delta p}{1 - \delta p + \delta p q(\theta)\kappa(\theta)},$$

where  $\kappa(\theta) = \int_0^1 r(\theta, \theta') f(\theta') d\theta'$  is the probability that an incumbent of ability  $\theta$  loses an election, conditional on the challenger running; and  $y_1, y_0$  are the expected flow policy payoffs of an incumbent of ability  $\theta$  if the challenger runs or does not run, respectively. Remember also that

$$\bar{T}_{\theta_0} = \int_0^1 (R(\theta) + \gamma Q(\theta) + \gamma S(\theta_0, \theta)) r(\theta_0, \theta) f(\theta) d\theta.$$

Suppose first that the equilibrium is of type 2, and let  $\theta_1 = \theta_1(\theta_0)$ . Then  $r(\theta_0, \theta) = 0$  for  $\theta < \theta_0$ ,  $r(\theta_0, \theta) = \frac{1}{2}$  for  $\theta \in [\theta_0, \theta_1]$  and  $r(\theta_0, \theta) = 1$  for  $\theta > \theta_1$ :

$$\bar{T}_{\theta_0} = \frac{1}{2} \int_{\theta_0}^{\theta_1} (R(\theta) + \gamma Q(\theta) + \gamma S(\theta_0, \theta)) f(\theta) d\theta + \int_{\theta_1}^1 (R(\theta) + \gamma Q(\theta) + \gamma S(\theta_0, \theta)) f(\theta) d\theta.$$

Letting  $R_* = \frac{\partial R}{\partial \theta_0}$  and so on, we then want to show that  $\frac{\partial \bar{T}_{\theta_0}}{\partial \theta_0} < 0$  for all  $\theta_0$ , where

$$\begin{aligned} \frac{\partial \bar{T}_{\theta_0}}{\partial \theta_0} &= \frac{1}{2} \int_{\theta_0}^{\theta_1} (R_*(\theta) + \gamma Q_*(\theta) + \gamma S_*(\theta_0, \theta)) f(\theta) d\theta + \int_{\theta_1}^1 (R_*(\theta) + \gamma Q_*(\theta) + \gamma S_*(\theta_0, \theta)) f(\theta) d\theta \\ &\quad - \frac{1}{2} (R(\theta_0) + \gamma Q(\theta_0) + \gamma S(\theta_0, \theta_0)) f(\theta_0) - \frac{1}{2} \theta_1'(\theta_0) (R(\theta_1) + \gamma Q(\theta_1) + \gamma S(\theta_0, \theta_1)) f(\theta_1). \end{aligned}$$

Note that  $R_*(\theta) = 0$  for  $\theta > \theta_1$  (because  $q(\theta)\kappa(\theta) \equiv 0$ ), and  $S(\theta_0, \theta) = S_*(\theta_0, \theta) = 0$  for  $\theta \in [\theta_0, \theta_1]$ . Then we need to show

$$\begin{aligned} &\frac{1}{2} \int_{\theta_0}^{\theta_1} (R_*(\theta) + \gamma Q_*(\theta)) f(\theta) d\theta + \int_{\theta_1}^1 (\gamma Q_*(\theta) + \gamma S_*(\theta_0, \theta)) f(\theta) d\theta \\ &\quad - \frac{1}{2} (R(\theta_0) + \gamma Q(\theta_0)) f(\theta_0) - \frac{1}{2} \theta_1'(\theta_0) (R(\theta_1) + \gamma Q(\theta_1)) f(\theta_1) < 0 \end{aligned}$$

Because we want to show this holds for  $\gamma$  low enough, it is necessary and sufficient

to prove that

$$(B1) \quad \int_{\theta_0}^{\theta_1} R_*(\theta) f(\theta) d\theta < R(\theta_0) f(\theta_0) + R(\theta_1) f(\theta_1) \theta'_1(\theta_0)$$

and that  $Q_*(\theta)$ ,  $Q(\theta)$ , and  $S_*(\theta_0, \theta)$  ( $\theta > \theta_1$ ) are bounded.<sup>1</sup> Before proceeding further, note that  $R_*$ ,  $Q_*$  and  $S_*$  (hence also  $q_*$  and  $\kappa_*$ ) must be well defined for our approach to be valid. This boils down to showing that  $\theta'_1(\theta_0)$  exists, which follows from applying the Implicit Function Theorem to the characterization of  $\theta_1$  in Lemma B1.

We will first deal with office rents. We can calculate

$$R_*(\theta) = \frac{b\delta p q(\theta) \kappa(\theta)}{(1 - \delta p + \delta p q(\theta) \kappa(\theta))^2} \left( -\frac{q_*(\theta)}{q(\theta)} - \frac{\kappa_*(\theta)}{\kappa(\theta)} \right).$$

Here  $\kappa(\theta) = 1 - \frac{F(\theta_0) + F(\theta_1)}{2}$ , so  $\kappa_*(\theta) = -\frac{f(\theta_0) + f(\theta_1) \theta'_1(\theta_0)}{2}$ , and  $q(\theta) = \frac{\theta_1 - \theta}{\theta_1 - \theta_0}$ , so  $q_*(\theta) = \frac{\theta'_1(\theta_0)(\theta - \theta_0) + \theta_1 - \theta}{(\theta_1 - \theta_0)^2}$ . A digression here will be necessary. Using our characterization of  $q'$  and  $\theta_1$  (Proposition 5—pinning down  $\theta_1$ ), we can show that  $\theta_1 - \theta_0$  is bounded away from zero and  $\theta'_1$  is bounded and bounded away from zero:

**Lemma B1.** *There are  $m, m', M > 0$  dependent only on  $\mu, \delta, p$  and  $F$  such that  $\theta_1(\theta_0) - \theta_0 \geq m'$  and  $\theta'_1(\theta_0) \in [m, M]$ .*

*Proof.* Note that if  $\theta_1(\theta_{0k}) - \theta_{0k} \xrightarrow[k \rightarrow \infty]{} 0$  for some sequence  $(\theta_{0k})_k$ , then in the limit we would have  $|q'| \leq \frac{1}{\delta p \min(\mu, 1 - \mu) \int_0^1 \min\left(\frac{1 - F(\theta)}{1 - \delta p[\mu + (1 - 2\mu)F(\theta)]}, \frac{1 - F(\theta)}{1 - \delta p(1 - \mu)}\right) d\theta} < \infty$ , so  $q'(\theta_1 - \theta_0) \rightarrow 0$ , a contradiction. If  $1 \geq \theta_1 - \theta_0 \geq m'$ , then  $1 \leq q' \leq \frac{1}{m'}$ .  $\theta'_1$  must solve  $q'(\theta'_1 - 1) + \left(\frac{\partial q'}{\partial \theta_1} \theta'_1 + \frac{\partial q'}{\partial \theta_0}\right)(\theta_1 - \theta_0) = 0$ , or  $\theta'_1 = \frac{q' - \frac{\partial q'}{\partial \theta_0}}{q' + \frac{\partial q'}{\partial \theta_1}}$ . Here  $-\frac{\partial q'}{\partial \theta_0} = q'^2 \frac{\delta p \mu (1 - F(\theta_0))}{1 - \delta p[\mu + (1 - 2\mu)F(\theta_0)]} \leq \frac{\delta p \mu}{(1 - \delta p)m'^2}$  and  $\frac{\partial q'}{\partial \theta_1} = q'^2 \frac{\delta p(1 - \mu)(1 - F(\theta_1))}{1 - \delta p + \delta p \mu} \leq \frac{\delta p(1 - \mu)}{(1 - \delta p)m'^2}$ . This yields the result.  $\square$

Using Lemma B1 and previous results, and denoting  $\underline{m} = \min(m, 1)$ ,

$$\begin{aligned} -\frac{q_*(\theta)}{q(\theta)} &= -\frac{1}{q(\theta)} \frac{\theta'_1(\theta_0)(\theta - \theta_0) + \theta_1 - \theta}{(\theta_1 - \theta_0)^2} \leq -\frac{1}{q(\theta)} \frac{\underline{m}(\theta - \theta_0) + (\theta_1 - \theta)}{\theta_1 - \theta_0} = \\ &= -\frac{\underline{m}}{q(\theta)(\theta_1 - \theta_0)} - \frac{1 - \underline{m}}{\theta_1 - \theta_0} \leq -\frac{1}{1 - \theta_0} \left( \frac{\underline{m}}{q(\theta)} + 1 - \underline{m} \right) \\ -\frac{\kappa_*(\theta)}{\kappa(\theta)} &= \frac{f(\theta_0) + f(\theta_1) \theta'_1(\theta_0)}{2 - F(\theta_0) - F(\theta_1)} \leq \frac{f(\theta_0) + f(\theta_1) \theta'_1(\theta_0)}{1 - F(\theta_0)}. \end{aligned}$$

<sup>1</sup>Because both sides of (B1) are continuous in  $\theta_0$ , if the inequality holds strictly for all  $\theta_0$ , the difference between the two sides is bounded away from zero.

Then we can deal with the terms involving  $f(\theta_1)$  as follows:

$$\int_{\theta_0}^{\theta_1} \frac{b\delta pq(\theta)\kappa(\theta)}{(1-\delta p + \delta pq(\theta)\kappa(\theta))^2} \frac{f(\theta_1)\theta'_1(\theta_0)}{(1-F(\theta_0))} f(\theta)d\theta < R(\theta_1)f(\theta_1)\theta'_1(\theta_0),$$

because  $\frac{\delta pq(\theta)\kappa(\theta)}{(1-\delta p + \delta pq(\theta)\kappa(\theta))^2} < \frac{1}{1-\delta p}$  and  $\int_{\theta_0}^{\theta_1} f(\theta)d\theta \leq 1 - F(\theta_0)$ . So it is enough to show

$$\int_{\theta_0}^{\theta_1} \frac{b\delta pq(\theta)\kappa(\theta)}{(1-\delta p + \delta pq(\theta)\kappa(\theta))^2} \left( -\frac{\frac{m}{q(\theta)} + 1 - \underline{m}}{1 - \theta_0} + \frac{f(\theta_0)}{1 - F(\theta_0)} \right) f(\theta)d\theta < R(\theta_0)f(\theta_0).$$

Using that  $\frac{f(\theta_0)}{1-F(\theta_0)} \leq \frac{\phi}{1-\theta_0}$ , it is enough to show that for any  $0 \leq q \leq 1$

$$\begin{aligned} \left( \frac{b\delta pq\kappa}{(1-\delta p + \delta pq\kappa)^2} \left( 1 - \frac{\underline{m}}{\phi q} - \frac{1 - \underline{m}}{\phi} \right) \frac{f(\theta_0)}{1 - F(\theta_0)} \right) (F(\theta_1) - F(\theta_0)) &< \frac{bf(\theta_0)}{1 - \delta p + \delta p\kappa} \\ \frac{\delta pq\kappa}{(1-\delta p + \delta pq\kappa)^2} \left( 1 - \frac{\underline{m}}{\phi q} - \frac{1 - \underline{m}}{\phi} \right) &< \frac{1}{1 - \delta p + \delta p\kappa} \end{aligned}$$

The left-hand side is single-peaked in  $q$  with a maximum at  $q^* = \frac{1-\delta p}{\delta p\kappa} + \frac{2\underline{m}}{\phi-1+\underline{m}}$ . If this  $q^*$  is greater than 1, then we need

$$\frac{\delta p\kappa}{(1-\delta p + \delta p\kappa)^2} \left( 1 - \frac{1}{\phi} \right) < \frac{1}{1 - \delta p + \delta p\kappa},$$

which always holds. If  $0 < q^* < 1$ , then the maximized value of the left-hand side is  $\frac{1}{\frac{4\phi}{\phi-1+\underline{m}}(1-\delta p) + \frac{4\underline{m}\phi}{(\phi-1+\underline{m})^2}\delta p\kappa}$ . Since  $\underline{m} \leq 1$ ,  $\frac{4\phi}{\phi-1+\underline{m}} \geq 4 > 1$ , so the required inequality is guaranteed to hold if  $\frac{4\underline{m}\phi}{(\phi-1+\underline{m})^2}$  is at least 1. This expression is decreasing in  $\phi$  (again given  $\underline{m} \leq 1$ ) and equals  $\frac{4}{\underline{m}} > 1$  if  $\phi = 1$ , so there is  $\phi^*(\underline{m}) > 1$  such that the inequality holds whenever  $\phi \leq \phi^*(\underline{m})$ .

We now turn to policy payoffs. For  $\theta \in [\theta_0, \theta_1]$ ,

$$\begin{aligned} Q(\theta) &= [q(\theta)y_1 + (1 - q(\theta))y_0] \frac{\delta p}{1 - \delta p + \delta pq(\theta)\kappa(\theta)} \\ \implies Q_*(\theta) &= -\frac{q(\theta)y_1 + (1 - q(\theta))y_0}{(1 - \delta p + \delta pq(\theta)\kappa(\theta))^2} \delta^2 p^2 q(\theta)\kappa(\theta) \left( \frac{q_*(\theta)}{q(\theta)} + \frac{\kappa_*(\theta)}{\kappa(\theta)} \right) \\ &\quad - \delta p \frac{q_*(\theta)(y_0 - y_1)}{1 - \delta p + \delta pq(\theta)\kappa(\theta)} + \delta p \frac{q(\theta)y_{1*} + (1 - q(\theta))y_{0*}}{1 - \delta p + \delta pq(\theta)\kappa(\theta)}. \end{aligned}$$

$f$  is bounded by assumption and  $q, \kappa \leq 1$ . Also  $|Q(\theta)|, |y_0|, |y_1| \leq \frac{I^2}{1-\delta p}$ . It remains to bound  $y_{0*}$  and  $y_{1*}$ . Using that  $y_0 = S(0, \theta)$ ,  $y_1 = \int_0^1 S(\theta', \theta) f(\theta') d\theta$ , and  $S(\theta', \theta) = \mu \left( -\frac{U(\theta) - U(\theta')}{\lambda} + 2\sqrt{\frac{U(\theta) - U(\theta')}{\lambda}} I - I^2 \right)$  for any  $\theta' \leq \theta$  (see Lemma 1), we obtain:

$$y_0 = \mu \left( -I^2 + 2I\sqrt{\frac{\tilde{U}(\theta_0)}{\lambda}} - \frac{\tilde{U}(\theta_0)}{\lambda} \right), \quad y_{0*} = \mu U'(\theta_0) \left[ I\sqrt{\frac{1}{\tilde{U}(\theta_0)\lambda}} - \frac{1}{\lambda} \right],$$

$$y_1 = \mu \int_0^{\theta_0} \left( -I^2 + 2I\sqrt{\frac{\tilde{U}(\theta_0) - \tilde{U}(\theta)}{\lambda}} - \frac{\tilde{U}(\theta_0) - \tilde{U}(\theta)}{\lambda} \right) f(\theta) d\theta,$$

$$y_{1*} = \mu U'(\theta_0) \int_0^{\theta_0} \left( I\sqrt{\frac{1}{(\tilde{U}(\theta_0) - \tilde{U}(\theta))\lambda}} - \frac{1}{\lambda} \right) f(\theta) d\theta.$$

Now, using that  $1 \leq U'(\theta) \leq \frac{1}{1-\delta p}$  for  $\theta < \theta_0$ , and denoting  $\max f = \bar{f}$ ,

$$-\frac{\mu}{\lambda(1-\delta p)} \leq y_{1*} \leq \frac{\mu}{1-\delta p} \int_0^{\theta_0} I\sqrt{\frac{1}{(\theta_0 - \theta)\lambda}} \bar{f} d\theta = \frac{\mu}{1-\delta p} \frac{2I\bar{f}\sqrt{\theta_0}}{\sqrt{\lambda}} \leq \frac{\mu}{1-\delta p} \frac{2I\bar{f}}{\sqrt{\lambda}}$$

$$-\frac{\mu}{\lambda(1-\delta p)} \leq y_{0*} \leq \frac{\mu}{1-\delta p} \frac{I}{\sqrt{\theta_0}\sqrt{\lambda}}.$$

$Q_*(\theta)$  for  $\theta > \theta_1$  and  $S_*(\theta_0, \theta)$  for  $\theta > \theta_1$  can be bounded with similar arguments. All of our bounds are uniform in  $\theta_0$  except for the upper bound on  $y_{0*}$ , which is proportional to  $\frac{1}{\sqrt{\theta_0}}$  and explodes as  $\theta_0 \rightarrow 0$ .

We finish our proof of equilibrium uniqueness in this region with the following argument. If  $\gamma = 0$ , given values of all other parameters, there is a unique equilibrium whenever  $\phi < \phi^*(\underline{m})$ . Let  $\theta^*$  be the value of  $\theta_0$  in this equilibrium. If  $\theta^* > 0$ , the *marginal* policy payoffs that show up in  $\frac{\partial \bar{T}}{\partial \theta_0}$  are bounded in a neighborhood of  $\theta^*$ , and the *total* policy payoffs in  $\bar{T}(\theta)$  are bounded everywhere (i.e.,  $\bar{T}$  may be nonmonotonic near 0, but this is far from  $\theta^*$ , where  $\bar{T}$  crosses  $c$ ). If  $\theta^* = 0$ , then  $\bar{T}(\theta^*) < c$  for any  $\gamma > 0$  (because policy payoffs are negative), so the equilibrium is type 3, which does not have these issues.

Next, suppose the equilibrium is type 1. Then

$$\begin{aligned}\bar{T}_{\theta_0} &= \frac{1}{2} \int_{\theta_0}^1 (R(\theta) + \gamma Q(\theta) + \gamma S(\theta_0, \theta)) f(\theta) d\theta \\ \frac{\partial \bar{T}_{\theta_0}}{\partial \theta_0} &= \frac{1}{2} \int_{\theta_0}^1 (R_*(\theta) + \gamma Q_*(\theta) + \gamma S_*(\theta_0, \theta)) f(\theta) d\theta - \frac{1}{2} (R(\theta_0) + \gamma Q(\theta_0) + \gamma S(\theta_0, \theta_0)) f(\theta_0)\end{aligned}$$

Bounding the policy payoffs in this case is not hard (the issues that arise as  $\theta_0$  approaches zero do not apply here). We then have to show

$$\int_{\theta_0}^1 R_*(\theta) f(\theta) d\theta < R(\theta_0) f(\theta_0).$$

We now have

$$q_*(\theta) \geq \frac{1 - q(1)}{1 - \theta_0}, \quad \kappa(\theta) = \frac{1 - F(\theta_0)}{2} \implies \kappa_*(\theta) = -\frac{1}{2} f(\theta_0), \quad -\frac{\kappa_*(\theta)}{\kappa(\theta)} \leq \frac{f(\theta_0)}{1 - F(\theta_0)}.$$

(The bound on  $q_*(\theta)$  uses the fact that, when  $\theta_1 = 1$ ,  $|q'(\theta)|$  is decreasing in  $\theta_0$ —see Proposition 5.) Arguing as before, it is enough to show

$$\begin{aligned}\frac{b\delta p q \kappa}{(1 - \delta p + \delta p q \kappa)^2} \left(1 - \frac{1 - q(1)}{\phi q}\right) \frac{f(\theta_0)}{1 - F(\theta_0)} (1 - F(\theta_0)) &< \frac{b f(\theta_0)}{1 - \delta p + \delta p \kappa} \\ \iff \frac{\delta p q \kappa}{(1 - \delta p + \delta p q \kappa)^2} \left(1 - \frac{1 - q(1)}{\phi q}\right) &< \frac{1}{1 - \delta p + \delta p \kappa}\end{aligned}$$

subject to  $q \geq q(1)$ .

Again  $\frac{\delta p q \kappa}{(1 - \delta p + \delta p q \kappa)^2} \left(1 - \frac{1 - q(1)}{\phi q}\right)$  is single peaked in  $q$  with a maximum at  $q^* = \frac{1 - \delta p}{\delta p \kappa} + \frac{2(1 - q(1))}{\phi}$ . There are three cases. If  $q^* > 1$ , then we need

$$\frac{\delta p \kappa}{(1 - \delta p + \delta p \kappa)^2} \left(1 - \frac{1 - q(1)}{\phi}\right) < \frac{1}{1 - \delta p + \delta p \kappa},$$

which always holds. If  $1 > q^* > q(1)$ , then  $q^* > \frac{\frac{1-\delta p}{\delta p \kappa} + \frac{2}{\phi}}{1 + \frac{2}{\phi}} > q(1)$ , and

$$\begin{aligned} & \frac{\delta p q^* \kappa}{(1 - \delta p + \delta p q^* \kappa)^2} \left( 1 - \frac{1 - q(1)}{\phi} \right) = \\ &= \frac{1}{4 \left( 1 - \delta p + \frac{\delta p \kappa}{\phi} (1 - q(1)) \right)} < \frac{1}{4 \left( 1 - \delta p + \frac{\delta p \kappa}{\phi} \left( 1 - \frac{\frac{1-\delta p}{\delta p \kappa} + \frac{2}{\phi}}{1 + \frac{2}{\phi}} \right) \right)} = \\ &= \frac{1}{4 \left( (1 - \delta p) \left( 1 - \frac{1}{\phi+2} \right) + \delta p \kappa \frac{1}{\phi+2} \right)} \end{aligned}$$

which is always smaller than  $\frac{1}{1 - \delta p + \delta p \kappa}$  if  $\phi < 2$ .

Finally, if  $q(1) > q^*$ , then we need

$$\begin{aligned} & \frac{\delta p q(1) \kappa}{(1 - \delta p + \delta p q(1) \kappa)^2} \left( 1 - \frac{1 - q(1)}{\phi q(1)} \right) < \frac{1}{1 - \delta p + \delta p \kappa} \\ \iff & \frac{\delta p q(1) \kappa}{(1 - \delta p + \delta p q(1) \kappa)^2} \frac{\phi + 1}{\phi} \left( 1 - \frac{1}{(\phi + 1)q(1)} \right) < \frac{1}{1 - \delta p + \delta p \kappa} \end{aligned}$$

The value of  $q(1)$  that maximizes the left-hand side is  $\frac{1-\delta p}{\delta p \kappa} + \frac{2}{\phi+1}$ , and the maximized value of the left-hand side is  $\frac{\phi+1}{\phi} \frac{1}{4(1-\delta p) + \frac{4}{\phi+1} \delta p \kappa}$ . This expression is decreasing in  $\phi$  and always less than  $\frac{1}{1 - \delta p + \delta p \kappa}$  for  $\phi = 1$ , so there is again a threshold  $\phi^* > 1$  such that the inequality holds if  $\phi < \phi^*$ .

The case of a type 3 equilibrium is the simplest one. The policy payoffs can be handled as before. For office rents, we need to show that

$$\int_0^{\theta_1} R_*(\theta) f(\theta) d\theta < R(\theta_1) f(\theta_1),$$

where  $R_*(\theta)$  now represents  $\frac{\partial R(\theta)}{\partial \theta_1}$ . (We can't use  $\theta_0$  as the parameter since it is 0, and  $\theta_1$  is more convenient than  $q(0)$ .) We can, as before, show that  $q_*(\theta) > 0$ , and  $\kappa(\theta) = 1 - \frac{F(\theta_1)}{2}$ , so  $\kappa_*(\theta) = -\frac{f(\theta_1)}{2}$  and  $-\frac{\kappa_*(\theta)}{\kappa(\theta)} = \frac{f(\theta_1)}{2 - F(\theta_1)} < f(\theta_1)$ . Then

$$\begin{aligned} & R_*(\theta) = \frac{b \delta p q(\theta) \kappa(\theta)}{(1 - \delta p + \delta p q(\theta) \kappa(\theta))^2} \left( -\frac{q_*(\theta)}{q(\theta)} - \frac{\kappa_*(\theta)}{\kappa(\theta)} \right) < \frac{b}{1 - \delta p} f(\theta_1) \\ \implies & \int_0^{\theta_1} R_*(\theta) f(\theta) d\theta < \frac{b}{1 - \delta p} f(\theta_1) F(\theta_1) < \frac{b}{1 - \delta p} f(\theta_1) = R(\theta_1) f(\theta_1). \end{aligned}$$

□

*Proof of Corollary 1.* Parts (i) and (ii) are immediate consequences of Proposition 6. For part (iii), note that  $U_1(\theta) = \theta + \delta V$  and  $U_0(\theta) = \theta + \delta V_1(\theta)$ , so  $U_1'(\theta) = 1$  and  $U_0'(\theta) = 1 + \delta V_1'(\theta)$ . For  $\theta < \theta_0$ ,  $V_1(\theta) = \mu E(\min(U_1(\theta), U_0(\theta')) | \theta' \sim F) + (1 - \mu) E(\max(U_1(\theta), U_0(\theta')) | \theta' \sim F)$ .  $U_1'(\theta) = 1$  then implies  $V_1'(\theta) = 0$ , so  $U_0'(\theta) > U_1'(\theta)$ . For  $\theta > \theta_0$ ,  $V_1(\theta) = \mu \min(U_1(\theta), U_0(0)) + (1 - \mu) \max(U_1(\theta), U_0(0))$ .  $U_1'(\theta) = 1$  again implies  $V_1'(\theta) > 0$  and  $U_0'(\theta) > U_1'(\theta)$  unless  $\mu = 1$ , in which case  $V_1(\theta) = U_0(0)$  and  $U_0'(\theta) = 1 = U_1'(\theta)$ .

For part (iv), if  $\mu = 1$ , we will argue that  $U_0(0) < U_1(\theta)$  for all  $\theta$ . This follows since  $U_0(0) = \delta V_1(0) \leq V_1(0) = E(\min(U_1(0), U_0(\theta')) | \theta' \sim F) \leq U_1(0)$ , and  $U_1$  is increasing. (Note that  $V, U_0, U_1, V_1 \geq 0$ , since electing the weaker candidate always gives a nonnegative flow payoff.) Hence  $V_1(\theta) = U_0(0)$  for  $\theta > \theta_0$ . It also follows that  $U_0(0) \leq V$ , as  $U_0(0) \leq U_1(0) = \delta V$ . Hence  $U_1(\theta) \geq U_0(\theta)$  for  $\theta > \theta_0$ , as  $V \geq V_1(\theta) = U_0(0)$  for  $\theta > \theta_0$ . Both inequalities are strict unless  $V = 0$ , which happens iff  $q_0 = 0$ . This argument also goes through for  $\mu$  in a neighborhood of 1.

There are two degenerate cases. If  $U^*$  is above  $U_1(1)$ , there always is competition. This is possible in under classic limits if  $c$  is low enough, since in an open election there is always a positive probability of winning, and in a closed election the challenger can always defeat the incumbent with non-negligible probability, since  $U_0(1) > U_1(1)$  (see part (iv) of Proposition 2). If  $U^*$  is below  $U_1(0)$ , there never is competition in a closed election. This is possible if  $c$  is high enough. □